

# Parallel computations for Metropolis Markov chains with Picard maps

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# Outline

- Overview
- Picard Map  $\Phi$  for Markov chain simulation
- Main theoretical results
- Simulations
- (Technical Appendix, only if time allows) Contraction of  $\Phi$

**S. Grazi, G. Zanella, *Parallel computations for Metropolis Markov chains with Picard maps.* arXiv:2506.09762**



# Overview

# Zeroth-order Parallel Sampling

- **Objective:** Sample from a distribution  $\pi(dx) = C \exp(-V(x))dx$  on  $\mathcal{X} = \mathbb{R}^d$ , for some unknown constant  $C$ .
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## Performance

**(Parallel round) complexity:** number of point-wise evaluations of  $V$  per parallel processor in order to obtain samples close to  $\pi$  (e.g. in total variation).

- **Important quantities:** dimension  $d$ , number of processors  $K$ .

# Diagram Parallel sampling

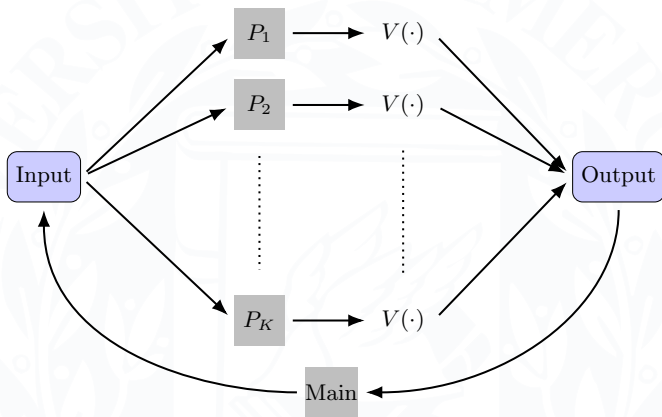


Figure 1: One parallel iteration of the algorithm

# Markov chain Monte Carlo

- **Approach:** Markov chain Monte Carlo i.e. **simulate** a Markov chain

$$X_{i+1} = X_i + f(X_i, W_i), \quad i = 0, 1, \dots \quad (1)$$

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*How do we parallelize the recursion in (1), given its sequential nature?*

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- **Preview of our results:**

Algorithm	complexity	$K$	method
Sequential algorithm	$\mathcal{O}(d)$	1	exact
Online Picard	$\mathcal{O}(\sqrt{d})$	$\mathcal{O}(\sqrt{d})$	exact
Approx. Online Picard	$\mathcal{O}(1)$	$\mathcal{O}(d)$	approximate





# Picard map for Markov chain simulation

# Picard Map

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- **Compute**  $X$  as the limit of the recursion  $X^{(j)} = \Phi(X^{(j-1)}, W)$  for  $j = 1, 2, \dots$

# Diagram Picard recursion

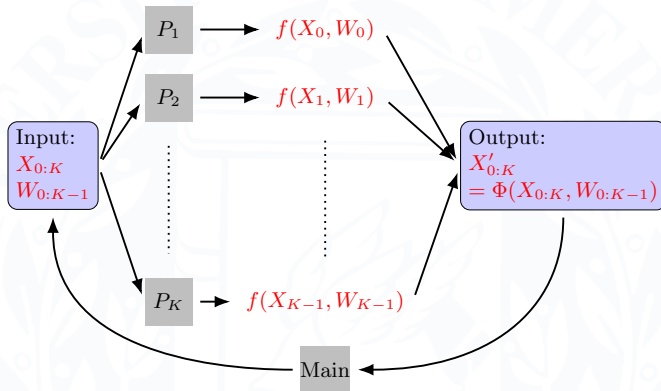


Figure 2: One parallel iteration of Picard recursion

# Illustration Picard map

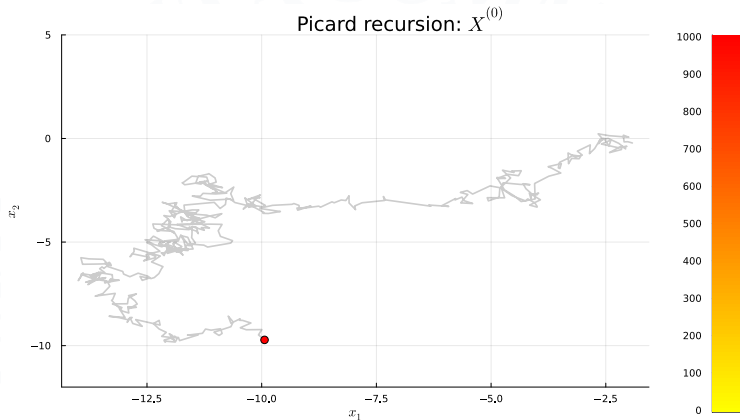


Figure 3:  $X_1^{(i)}, X_2^{(i)}, \dots$  of the Picard recursion for  $K = 1000$  steps applied to a  $d = 100$  dimensional RWM Markov chain. Gray line: Fixed point  $X_1, \dots, X_K$ . The dashed line corresponds to the part of the trajectory that has converged to its fixed point.



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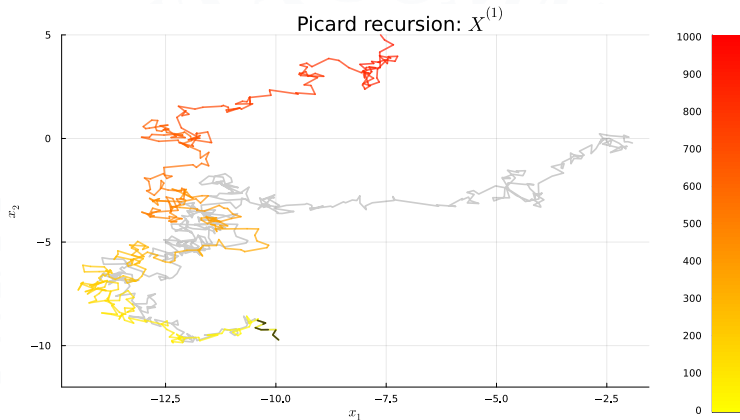


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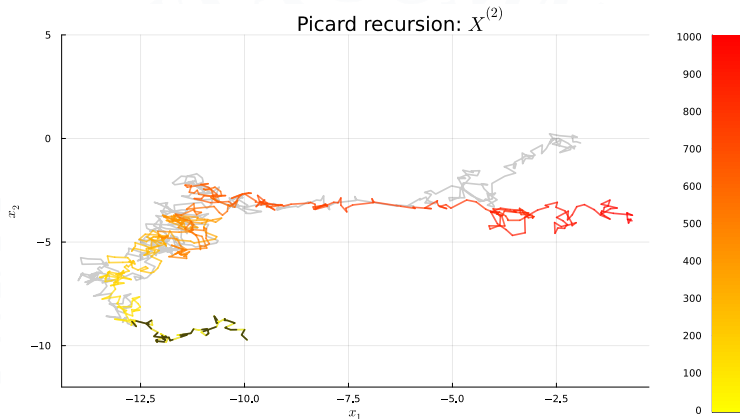


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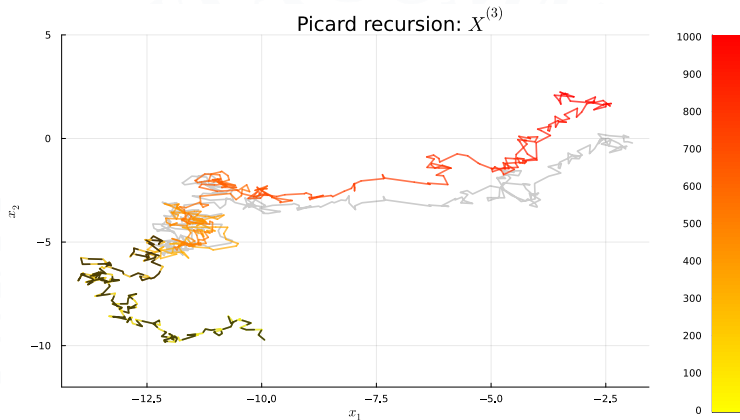


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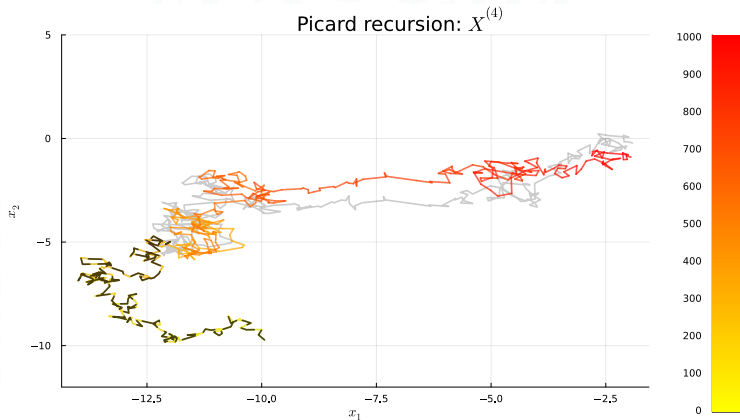


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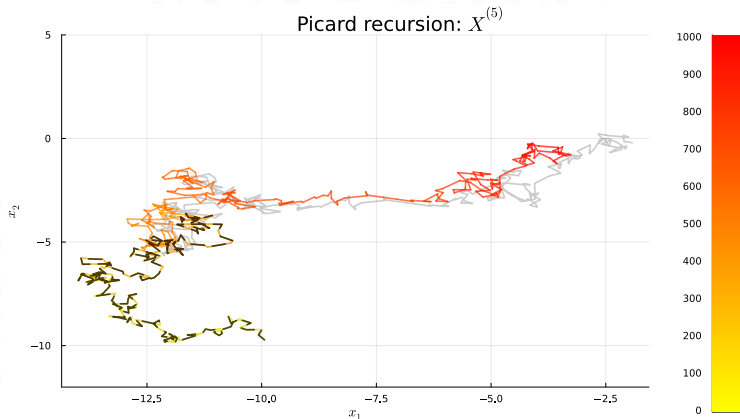


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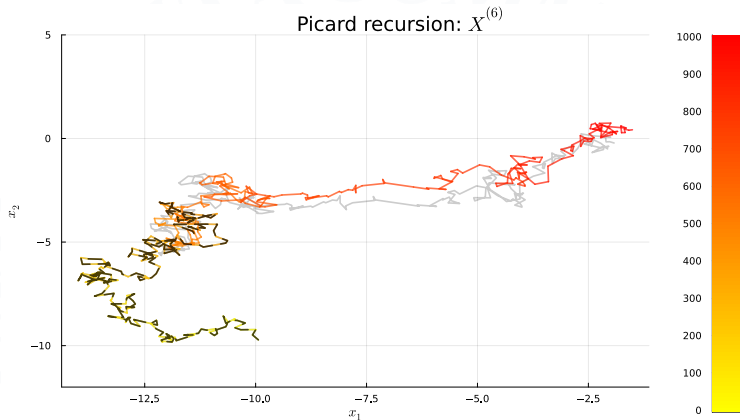


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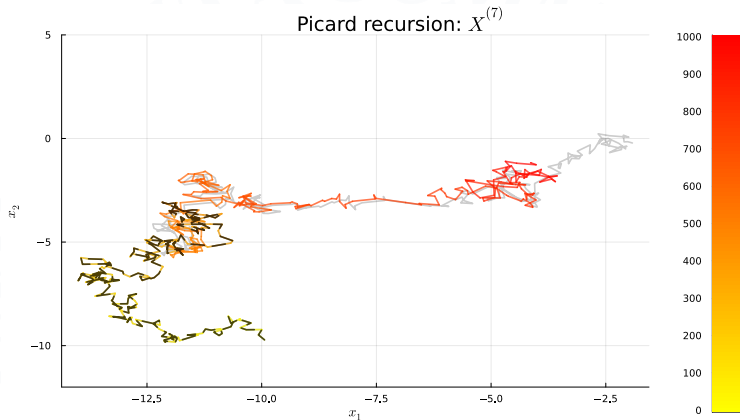


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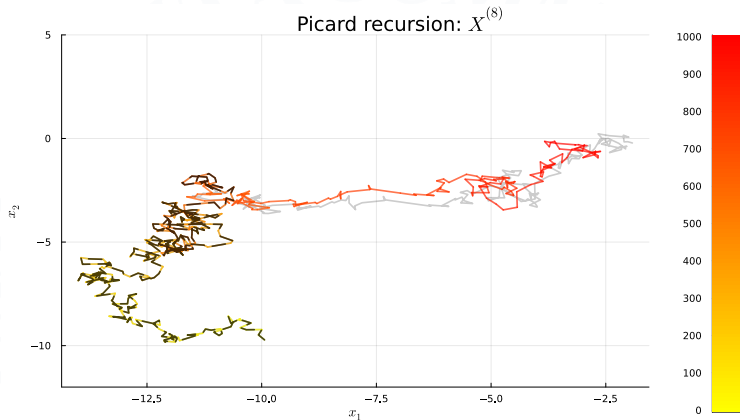


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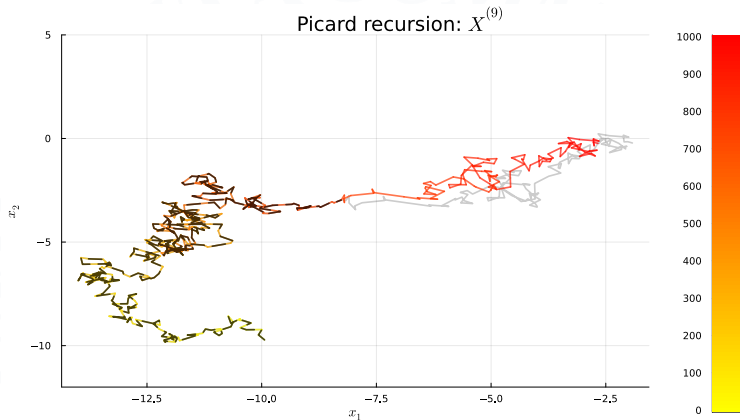


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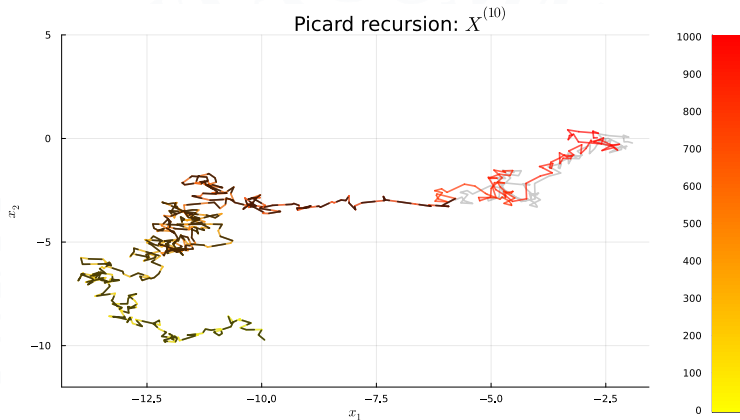


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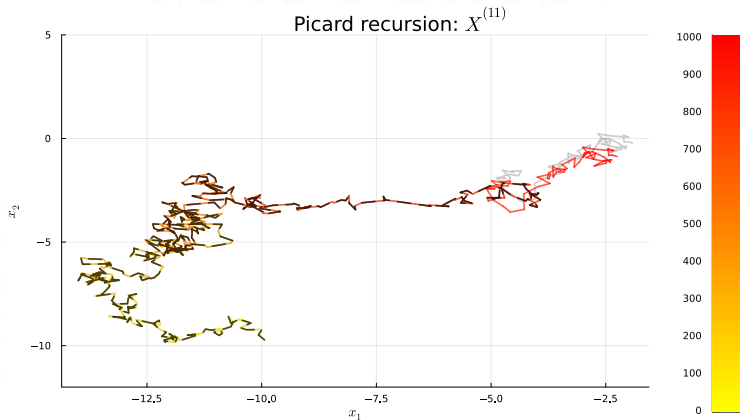


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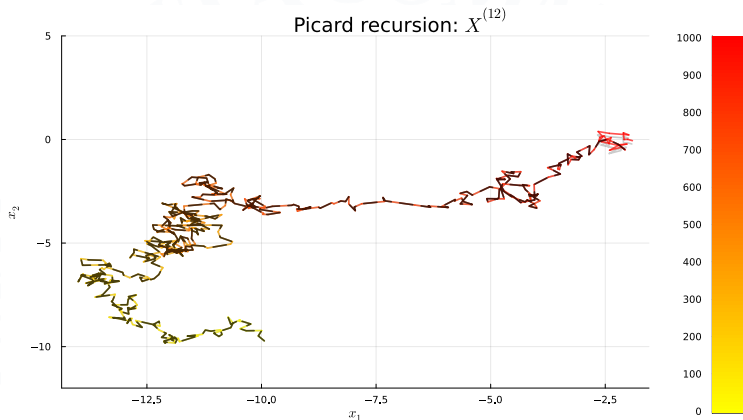


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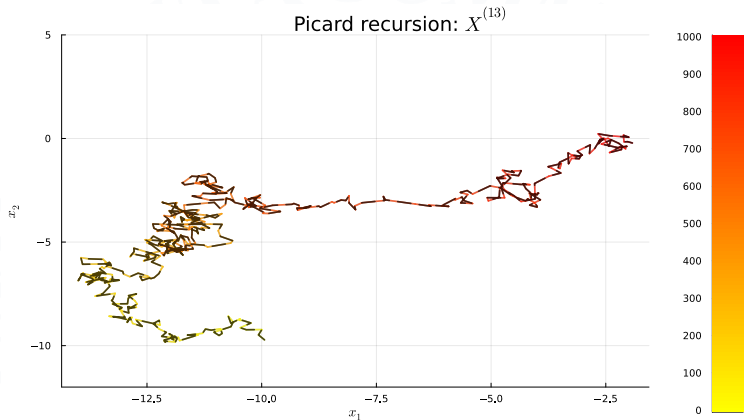


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- Piecewise constant  $x \mapsto f(x, w)$ :
  - The contraction of the Picard map for RWM is **non-standard**.
  - $X \mapsto \Phi(X, W)$  for RWM is **constant in a neighborhood of its fixed point**.
  - The fixed point of  $\Phi$  can be reached **exactly**.

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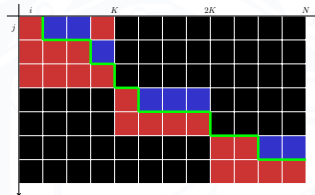


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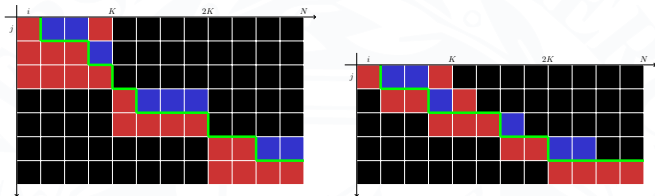


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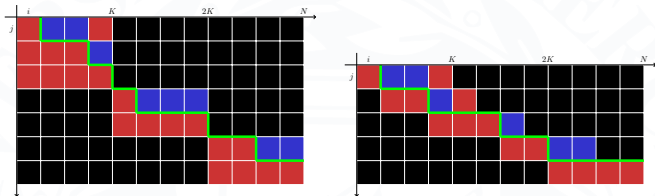


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- **Key challenges for analyzing the convergence:**
  - For each  $(j, i)$  square: probability of ■ (error) vs ■ (correct guess).

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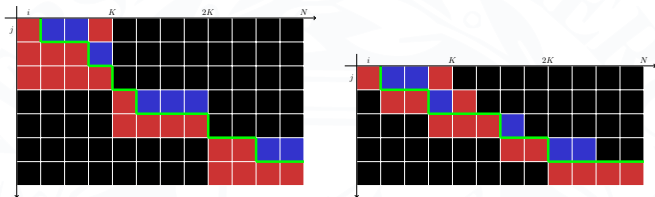


Figure 4: The color of the  $(j, i)$  entry represents the state of the  $i$ th step: ■ for  $f(X_i^{(j)}, W_i) = f(X_i^{(j-1)}, W_i)$  (correct guess), ■ for  $f(X_i^{(j)}, W_i) \neq f(X_i^{(j-1)}, W_i)$  (error). ■ where no processor has been allocated. —: number of steps simulated according to RWM.

- **Key challenges for analyzing the convergence:**
  - For each  $(j, i)$  square: probability of ■ (error) vs ■ (correct guess).
  - For each row  $j$ : probability of a strike of  $n > 1$  consecutive ■ (or equivalently the probability of the first ■).



# Theoretical results

# Probability of an error (■)

- Technical assumption:  $V$  is  $L$ -smooth and Hessian-Lipschitz.



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## Corollary 1 (Complexity OPA)

For log-concave distributions, the Online Picard algorithm with  $K = \mathcal{O}(\sqrt{d})$  outputs a random variable  $X$ , with  $\|\mathcal{L}(X) - \pi\|_{\text{TV}} \leq \epsilon$  after

$$J = \mathcal{O} \left( \frac{L}{m} \sqrt{d} \text{polylog}(\epsilon^{-1}) \right) \quad \text{parallel iterations.}$$

- Corollary 1 was obtained by combining Theorem 2 with known mixing time bounds of RWM (Andrieu et al. 2024)

# Approximate OPA (1)

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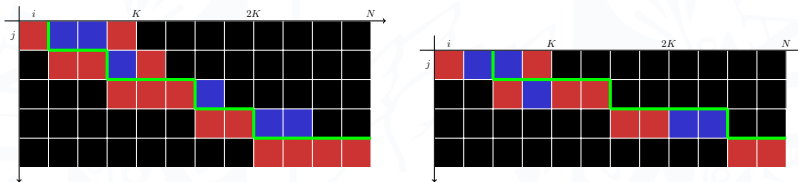


Figure 5: Illustration of OPA (left) vs AOPA with  $r = 50\%$  (right). The color of the  $(j, i)$  entry represents the state of the  $i$ th step: ■ for  $f(x_i^{(j)}, w_i) = f(x_i^{(j-1)}, w_i)$  (correct guess), ■ for  $f(x_i^{(j)}, w_i) \neq f(x_i^{(j-1)}, w_i)$  (error). ■ where no processor has been allocated.

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  - For Metropolis within Gibbs, we have instantaneous convergence for isotropic Gaussian targets, suggesting better performance for well-conditioned targets.



# Simulations

## Logistic Regression

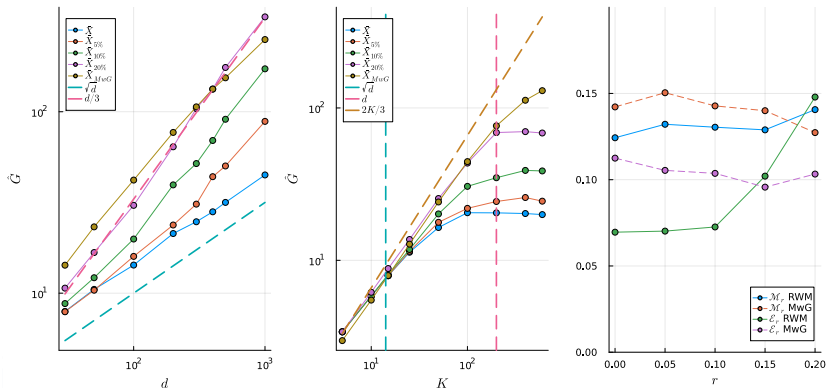


Figure 6: Performance of OPA ( $\bar{X}$ ) and its AOPA ( $\bar{X}_r$ ,  $r = 0\%, \dots, 20\%$ ) applied to RWM and MwG ( $\bar{X}_{MwG}$ ). Average speedup  $\hat{G} = N/T_{K,N}$ ,  $K = d$ ,  $d = 10^2, \dots, 10^3$  (Left panel) and  $d = 200$ ,  $K = 2, 3, \dots, 10^3$ . Right panel: Average error on 1st ( $\mathcal{M}_r$ ) and 2nd ( $\mathcal{E}_r$ ) moment estimation for the AOPA with  $r = 0\%, \dots, 20\%$

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Algorithm	complexity	$K$	method
Sequential algorithm	$\mathcal{O}(d)$	1	exact
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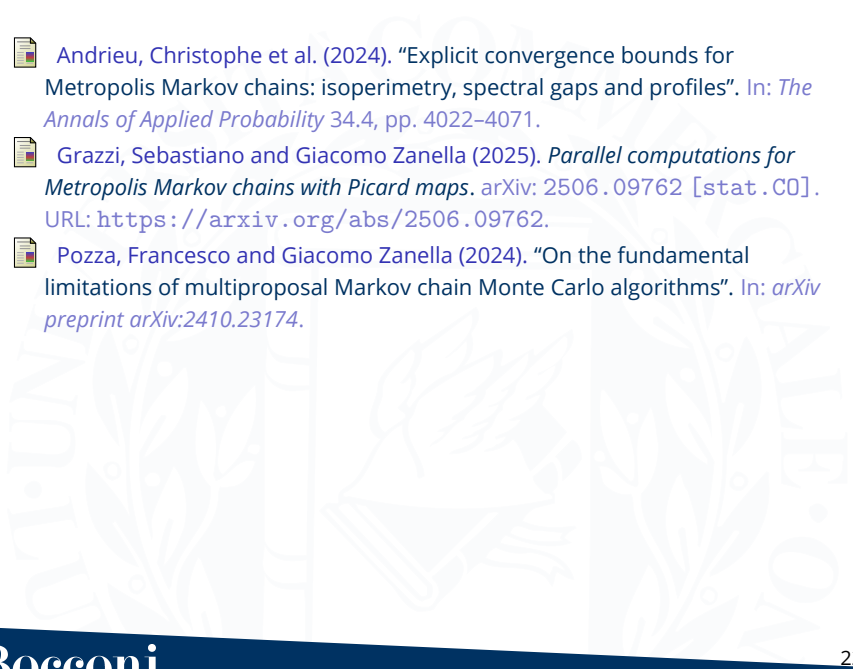



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  - Develop more advanced algorithms combining **"cheap" predictions** with **Picard maps** (e.g. Parareal framework)

- 
-  Andrieu, Christophe et al. (2024). “Explicit convergence bounds for Metropolis Markov chains: isoperimetry, spectral gaps and profiles”. In: *The Annals of Applied Probability* 34.4, pp. 4022–4071.
-  Grazi, Sebastiano and Giacomo Zanella (2025). *Parallel computations for Metropolis Markov chains with Picard maps*. arXiv: 2506.09762 [stat.CO]. URL: <https://arxiv.org/abs/2506.09762>.
-  Pozza, Francesco and Giacomo Zanella (2024). “On the fundamental limitations of multiproposal Markov chain Monte Carlo algorithms”. In: *arXiv preprint arXiv:2410.23174*.

# Contraction of the Picard map

### Lemma 1

Under Assumptions 3, for every  $x, y \in \mathcal{X}$ ,

$$\mathbb{P}(f(x, w) \neq f(y, w)) \leq \frac{hL^{1/2}}{d^{1/2}} \left( \sqrt{\frac{2}{\pi}} + \frac{h\gamma}{2} \right) \|x - y\|, \quad w \sim \nu.$$

### Lemma 2

Under Assumption 2 and for all  $x, y \in \mathcal{X}^{K+1}$  with  $x_0 = y_0, w_0 \in \mathcal{W}$  and  $1 < i \leq d$ ,

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**Lemma 3 and 4 implies Theorem 1, i.e.**

$$\mathbb{P}(f(X_i^{(j)}, w_i) \neq f(X_i, w_i) \mid X_0 = x_0, w_0 = w_0) \leq c_0 \frac{j}{d} + \delta(d) + 2^{-j}$$